Network Flow

T. M. Murali

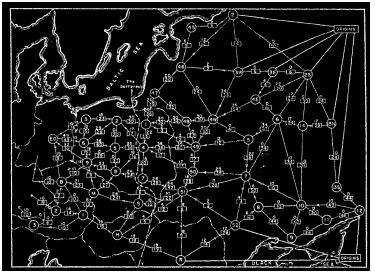
April 5, 7, 2021

Maximum Flow and Minimum Cut

- Two rich algorithmic problems.
- Fundamental problems in combinatorial optimization.
- Beautiful mathematical duality between flows and cuts.
- Numerous non-trivial applications:
 - Bipartite matching.
 - Data mining.
 - Project selection.
 - Airline scheduling.
 - Baseball elimination.
 - Image segmentation.
 - Network connectivity.
 - Open-pit mining.

- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- Security of statistical data.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Gene function prediction.

History



(Soviet Rail Network, Tolstoi, 1930; Harris and Ross, 1955; Alexander Schrijver, *Math Programming*, 91: 3, 2002.)

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Flow Networks

- Use directed graphs to model *transporation networks*:
 - edges carry traffic and have capacities.
 - nodes act as switches.
 - source nodes generate traffic, sink nodes absorb traffic.

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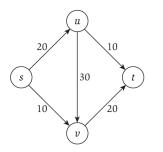


Figure 7.2 A flow network, with source *s* and sink *t*. The numbers next to the edges are the capacities.

- A flow network is a directed graph G(V, E)
 - Each edge $e \in E$ has a capacity c(e) > 0.
 - There is a single *source* node $s \in V$.
 - There is a single *sink* node $t \in V$.
 - ▶ Nodes other than *s* and *t* are *internal*.

Defining Flow

- In a flow network G(V, E), an *s*-*t* flow is a function $f : E \to \mathbb{R}^+$ such that
 - (*Capacity conditions*) For each $e \in E$, $0 \le f(e) \le c(e)$.
 - (Conservation conditions) For each internal node v,

$$\sum_{e \text{ into } v} f(e) = \sum_{e \text{ out of } v} f(e)$$

• The value of a flow is $\nu(f) = \sum_{e \text{ out of } s} f(e)$.

Maximum-Flow Problem

MAXIMUM FLOW

INSTANCE: A flow network G

SOLUTION: The flow with largest value in *G*, where the maximum is taking over all possible flows on *G*.

- Output should assign a flow value to each edge in the graph.
- The flow on each edge should satisfy the capacity condition.
- The flow into and out of each internal node should satisfy the conservation conditions.
- The value of the output flow, i.e., the total flow out of the source node in the output flow, must be the largest over all possible flows on *G*.

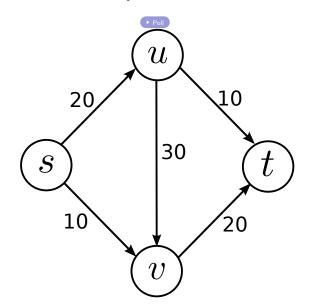
Maximum-Flow Problem

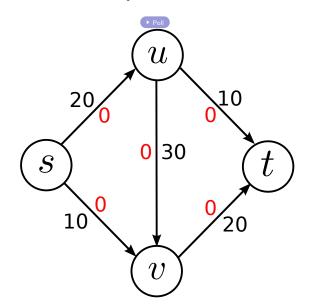
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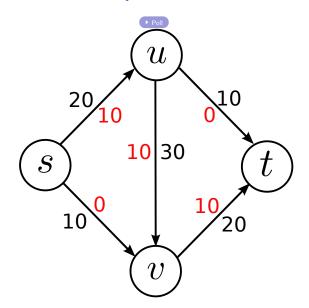
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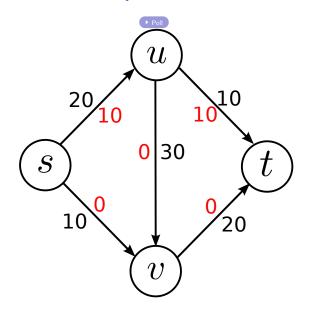
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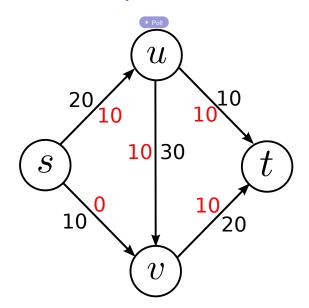
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- Assumptions:
 - No edges enter s, no edges leave t.
 - Provide the state of the sta
 - 3 All edge capacities are integers.

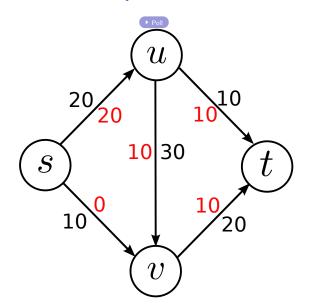


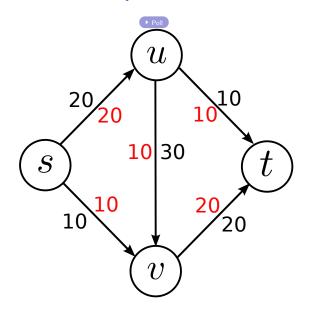












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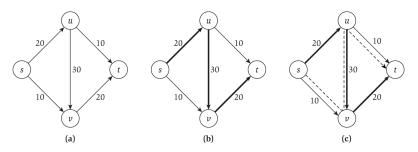


Figure 7.3 (a) The network of Figure 7.2. (b) Pushing 20 units of flow along the path s, u, v, t. (c) The new kind of augmenting path using the edge (u, v) backward.

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 - Solution Find an *s*-*t* path and push as much flow along it as possible (Figure 7.3(b)).

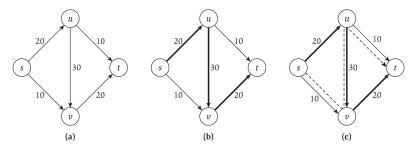


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- No known dynamic programming algorithm.
- Let us take a greedy approach.
 - Start with zero flow along all edges (Figure 7.3(a)).
 - **②** Find an *s*-*t* path and push as much flow along it as possible (Figure 7.3(b)).
 - Idea to increase flow: Push flow along edges with leftover capacity and undo flow on edges already carrying flow.

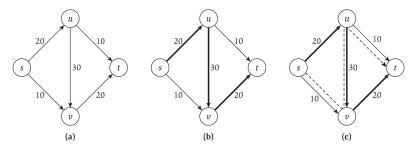
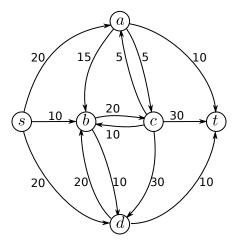


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Running Example for Ford-Fulkerson Algorithm



Residual Graph

- Given a flow network G(V, E) and a flow f on G, the residual graph G_f of G with respect to f is a directed graph such that
 - (*Nodes*) G_f has the same nodes as G.
 - (Forward edges) For each edge $e = (u, v) \in E$ such that f(e) < c(e), G_f contains the edge (u, v) with a residual capacity c(e) f(e).
 - (*Backward edges*) For each edge $e \in E$ such that f(e) > 0, G_f contains the edge e' = (v, u) with a *residual capacity* f(e).

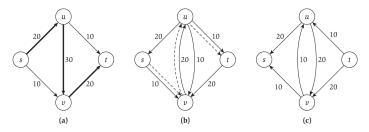


Figure 7.4 (a) The graph *G* with the path *s*, *u*, *v*, *t* used to push the first 20 units of flow. (b) The residual graph of the resulting flow *f*, with the residual capacity next to each edge. The dotted line is the new augmenting path. (c) The residual graph after pushing an additional 10 units of flow along the new augmenting path *s*, *v*, *u*, *t*.

Augmenting Paths in a Residual Graph

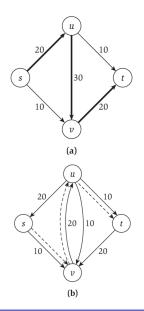
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- b = bottleneck(P, f) is the minimum residual capacity of any edge in *P*.

Augmenting Paths in a Residual Graph

- Let P be a simple s-t path in G_f .
- b = bottleneck(P, f) is the minimum residual capacity of any edge in P.
- The following operation $\operatorname{augment}(f, P)$ yields a new flow f' in G:

```
\begin{array}{l} \texttt{augment}(f,P)\\ \texttt{Let }b=\texttt{bottleneck}(P,f)\\ \texttt{For each edge }(u,v) \in P\\ \texttt{If }e=(u,v) \texttt{ is a forward edge then}\\ \texttt{ increase }f(e)\texttt{ in }G\texttt{ by }b\\ \texttt{Else }((u,v)\texttt{ is a backward edge, and let }e=(v,u))\\ \texttt{ decrease }f(e)\texttt{ in }G\texttt{ by }b\\ \texttt{Endif}\\ \texttt{Endif}\\ \texttt{Return}(f) \end{array}
```

- *e* is forward edge in $G_f \Rightarrow$ flow *increases* along *e* in *G*.
- e = (u, v) is backward edge in G_f ⇒ flow decreases along (v, u) in G. ♥ Work out example.



- A simple *s*-*t* path in the residual graph is an *augmenting path*.
- Let f' be the flow returned by $\operatorname{augment}(f, P)$.
- Claim: f' is a flow. Verify capacity and conservation conditions.

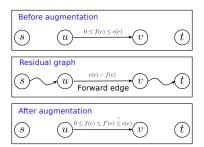
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 - ▶ Capacity condition on $e = (u, v) \in G_f$: Note that $b = bottleneck(P, f) \le residual capacity of <math>(u, v)$.

We skipped the proofs in class. Work them out on your own.

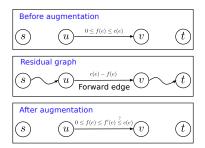
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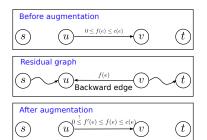


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$$0 \le f(e) \le f'(e) = f(e) + b \le f(e) + (c(e) - f(e)) = c(e).$$



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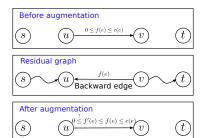


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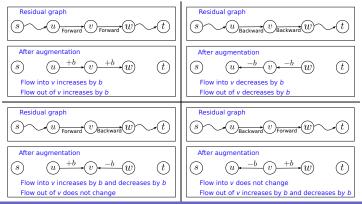
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* e is a backward edge: $c(e) \ge f(e) \ge f'(e) = f(e) - b \ge f(e) - f(e) = 0$.



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 - Only need to check edges and internal nodes in *P*.
 - Conservation condition on internal node $v \in P$. Four cases to work out.



Ford-Fulkerson Algorithm

```
Max-Flow

Initially f(e) = 0 for all e in G

While there is an s-t path in the residual graph G_f

Let P be a simple s-t path in G_f

f' = \operatorname{augment}(f, P)

Update f to be f'

Update the residual graph G_f to be G_{f'}

Endwhile

Return f
```

Work out running example.

Analysis of the Ford-Fulkerson Algorithm

- Running time
 - Does the algorithm terminate?
 - If so, how many loops does the algorithm take?
- Correctness: if the algorithm terminates, why does it output a maximum flow?

Termination of the Ford-Fulkerson Algorithm

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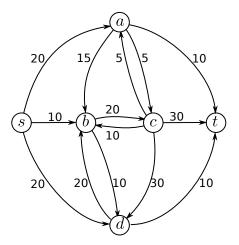
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 - Edge leaving s in P must be a forward edge (since no edge enters s in G).
 - v(f') = v(f) + bottleneck(P, f) > v(f).

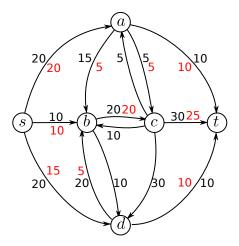
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- Claim: Maximum value of any flow is $C = \sum_{e \text{ out of } s} c(e)$.
- Claim: Algorithm terminates in at most C iterations.

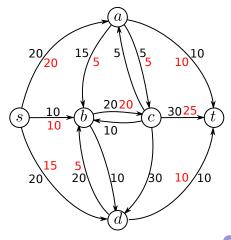
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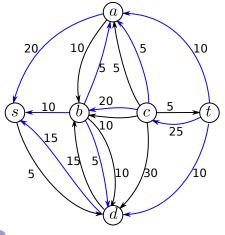
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- Claim: Algorithm runs in O(mC) time.

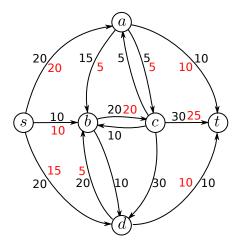


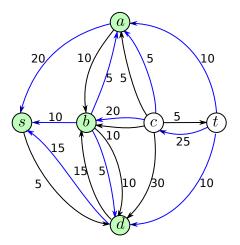


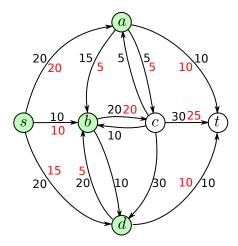


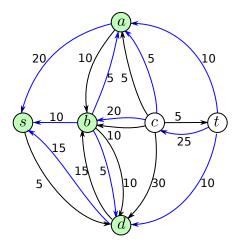


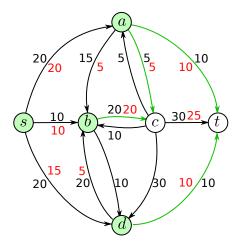
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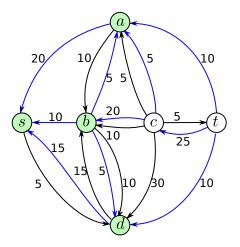


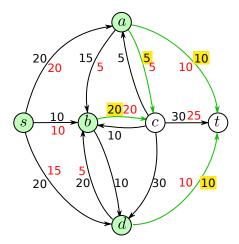


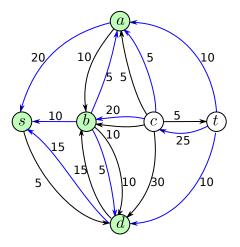












Correctness of the Ford-Fulkerson Algorithm

• How large can the flow be?

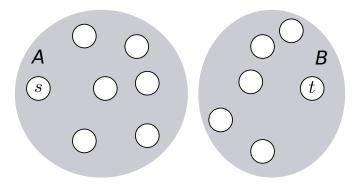
Correctness of the Ford-Fulkerson Algorithm

- How large can the flow be?
- Can we characterise the magnitude of the flow in terms of the structure of the graph? For example, for every flow f, ν(f) ≤ C = ∑_{e out of s} c(e).
- Is there a better bound?

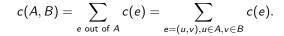
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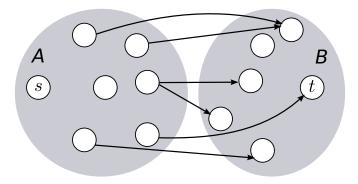
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- Is there a better bound?
- Proof strategy:
 - **1** Define s-t cut, its capacity, and flow in and out of the cut.
 - **2** For any s-t cut, prove any flow \leq its capacity.
 - **O** Define a specific *s*-*t* cut at the end of the Ford-Fulkerson algorithm.
 - Prove that the flow across this cut equals its capacity.

• An *s*-*t* cut is a partition of V into sets A and B such that $s \in A$ and $t \in B$.



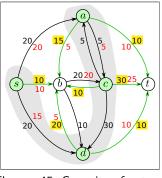
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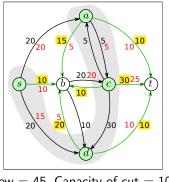
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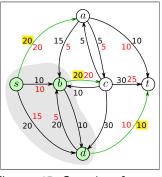
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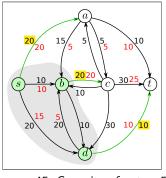
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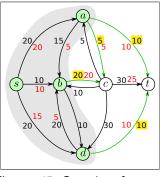
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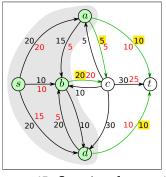
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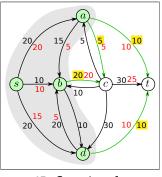
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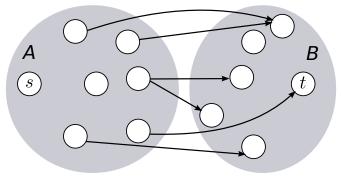
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• Intuition: For every flow f and for every s-t cut (A, B), $\nu(f) \leq c(A, B)$.



Some Useful Notation



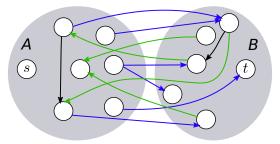
$$f^{\text{out}}(v) = \sum_{e \text{ out of } v} f(e)$$

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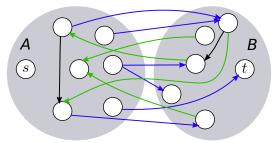
For $S \subseteq V$,

$$f^{\mathrm{out}}(S) = \sum_{e \text{ out of } S} f(e)$$

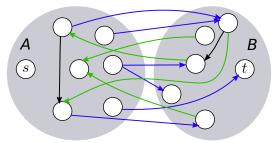
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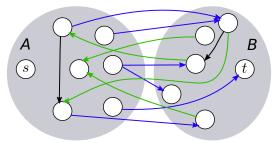
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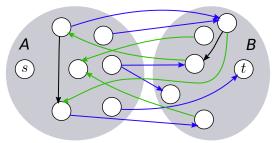
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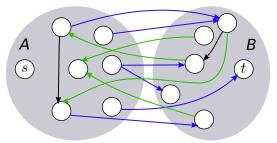
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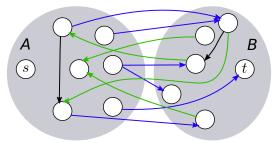
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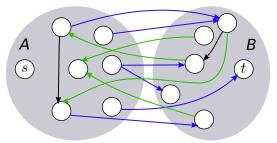
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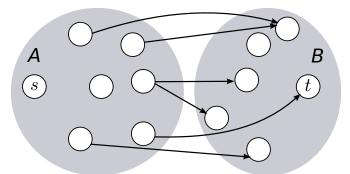


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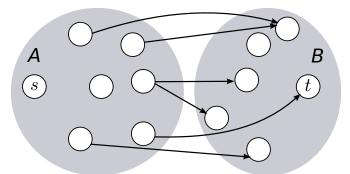
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Important Fact about Cuts



• For any flow f and any s-t cut (A, B), $\nu(f) \leq c(A, B)$.

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$$\leq f^{\text{out}}(A) = \sum_{e \text{ out of } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} c(e) = c(A, B).$$

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Max-Flows and Min-Cuts

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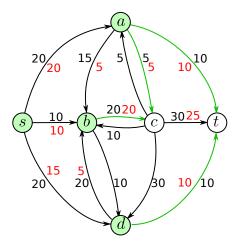
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- Question: Is the reverse true? Is the smallest capacity of a cut at most the maximum flow?
- Answer: Yes, and the Ford-Fulkerson algorithm computes this cut!

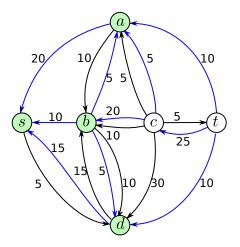
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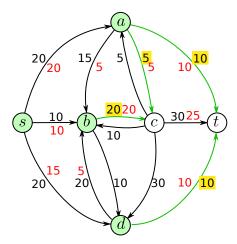
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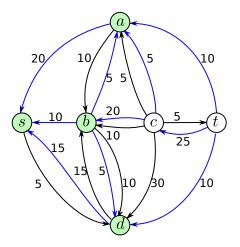
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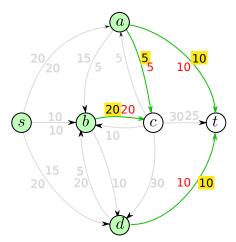
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- Claim: If f is an s-t flow such that G_f has no s-t path, then there is an s-t cut (A^*, B^*) such that $\nu(f) = c(A^*, B^*)$.
 - Claim applies to any flow f such that G_f has no s-t path, and not just to the flow \overline{f} computed by the Ford-Fulkerson algorithm.

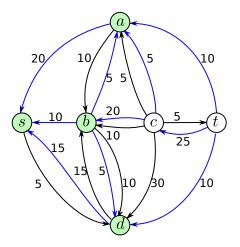


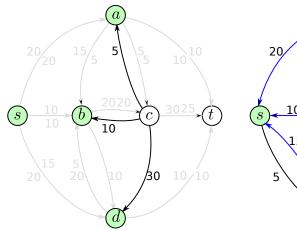


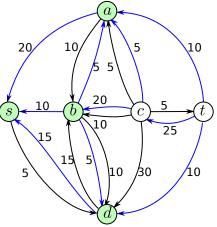




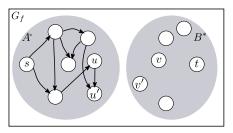




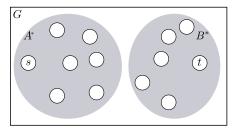




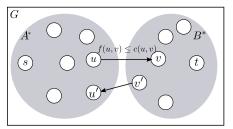
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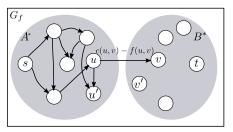
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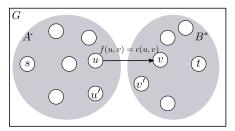
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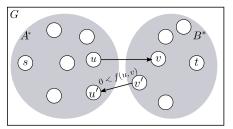
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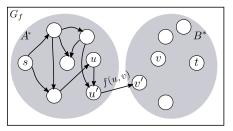
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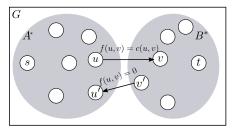
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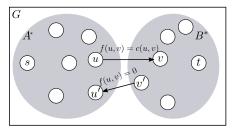
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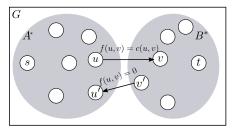
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$$\nu(f) = f^{\text{out}}(A^*) - f^{\text{in}}(A^*)$$

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= $\sum_{e \text{ out of } A^*} c(e) - \sum_{e \text{ into } A^*} 0 = c(A^*, B^*).$

Max-Flow Min-Cut Theorem

- The flow \overline{f} computed by the Ford-Fulkerson algorithm is a maximum flow.
- Given a flow of maximum value, we can compute a minimum s-t cut in O(m) time.
- In every flow network, there is a flow f and a cut (A, B) such that $\nu(f) = c(A, B)$.

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- Max-Flow Min-Cut Theorem: in every flow network, the maximum value of an *s*-*t* flow is equal to the minimum capacity of an *s*-*t* cut.
- Corollary: If all capacities in a flow network are integers, then there is a maximum flow f where f(e), the value of the flow on edge e, is an integer for every edge e in G.

Real-Valued Capacities

- If capacities are real-valued, Ford-Fulkerson algorithm may not terminate!
- But Max-Flow Min-Cut theorem is still true. Why?

Skip scaling algorithm

Bad Augmenting Paths

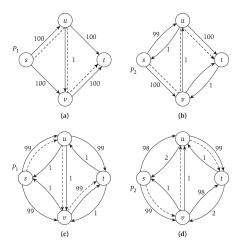


Figure 7.6 Parts (a) through (d) depict four iterations of the Ford-Fulkerson Algorithm using a bad choice of augmenting paths: The augmentations alternate between the path P_1 through the nodes s, u, v, t in order and the path P_2 through the nodes s, v, u, t in order.

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- $G_f(\Delta)$: residual network restricted to edges with residual capacities $\geq \Delta$.

Scaling Max-Flow Algorithm

```
Scaling Max-Flow
  Initially f(e) = 0 for all e in G
  Initially set \Delta to be the largest power of 2 that is no larger
          than the maximum capacity out of s: \Delta \leq \max_{e \text{ out of } s} c_e
     While \Delta > 1
         While there is an s-t path in the graph G_f(\Delta)
             Let P be a simple s-t path in G_f(\Delta)
            f' = \operatorname{augment}(f, P)
            Update f to be f' and update G_f(\Delta)
         Endwhile
         \Delta = \Delta/2
     Endwhile
Return f
```

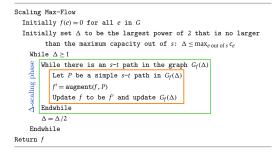
Correctness of the Scaling Max-Flow Algorithm

- Flow and residual capacities are integer valued throughout.
- When $\Delta = 1$, $G_f(\Delta)$ and G_f are identical.
- Therefore, when the scaling algorithm terminates, the flow is a maximum flow.

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- Claim: During a Δ -scaling phase, each iteration increases the flow by $\geq \Delta$.

Value of Flow at the End of a \triangle -Scaling Phase

Let f be the flow at the end of a Δ-scaling phase and f be the max flow.
Claim: Then there is an s-t cut in (A, B) in G such that

 $\nu(f) \leq \nu(\bar{f}) \leq c(A,B) \leq \nu(f) + m\Delta$

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- Let A^* be the set of nodes reachable from s in $G_f(\Delta)$; $B^* = V A^*$.
- Claim: (*A**, *B**) is an *s*-*t* cut in *G*.
- Claim: If e = (u, v) such that $u \in A^*$, $v \in B^*$, then $c(e) f(e) < \Delta$.

- Let f be the flow at the end of a Δ -scaling phase and \overline{f} be the max flow.
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Introduction

- Let f be the flow at the end of a Δ -scaling phase and \overline{f} be the max flow.
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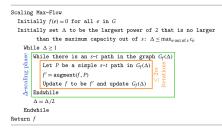
$$u(f) \leq \nu(\bar{f}) \leq c(A,B) \leq \nu(f) + m\Delta$$

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- Claim: $\nu(f) \ge c(A^*, B^*) m\Delta$.

$$\nu(f) = f^{\text{out}}(A^*) - f^{\text{in}}(A^*)$$

= $\sum_{e \text{ out of } A^*} f(e) - \sum_{e \text{ into } A^*} f(e)$
 $\geq \sum_{e \text{ out of } A^*} (c(e) - \Delta) - \sum_{e \text{ into } A^*} \Delta$
 $\geq \sum_{e \text{ out of } A^*} c(e) - \sum_{e \text{ in } G} \Delta$
 $\geq c(A^*, B^*) - m\Delta.$

Running time of the Scaling Max-Flow Algorithm II



- Claim: the number of augmentations in a Δ -scaling phase is $\leq 2m$.
 - Base case: In the first Δ -scaling phase, each edge incident on *s* can be used in at most one augmenting path.
 - ► Induction: At the end of the some Δ -scaling phase, let value of Δ be Γ and let f' be the flow: $\nu(f') \ge \nu(\bar{f}) m\Gamma$.

Running time of the Scaling Max-Flow Algorithm II

| Scaling Max-Flow |
|---|
| Initially $f(e) = 0$ for all e in G |
| Initially set Δ to be the largest power of 2 that is no largest |
| than the maximum capacity out of $s: \Delta \leq \max_{e \text{ out of } s} c_e$ |
| While $\Delta \ge 1$ |
| While there is an s-t path in the graph $G_{f}(\Delta)$ |
| Let P be a simple s-t path in $G_f(\Delta) \approx \frac{2}{3}$ |
| $ \begin{array}{c} \text{Let } P \text{ be a simple } s-t \text{ path in } G_{f}(\Delta) \\ f' = \text{augment}(f, P) \\ \text{Update } f \text{ to be } f' \text{ and update } G_{f}(\Delta) \end{array} $ |
| while there is an $s-t$ path in the graph $G_{f}(\Delta)$ Let P be a simple $s-t$ path in $G_{f}(\Delta)$ f' = argment(f, P) Update f to be f' and update $G_{f}(\Delta)$ Each while |
| Endwhile |
| $\Delta = \Delta/2$ |
| Endwhile |
| Return f |

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 - Base case: In the first Δ -scaling phase, each edge incident on *s* can be used in at most one augmenting path.
 - ▶ Induction: At the end of the some Δ -scaling phase, let value of Δ be Γ and let f' be the flow: $\nu(f') \ge \nu(\bar{f}) m\Gamma$.
 - In the next Δ-scaling phase, the value of Δ is Γ/2. Let f be the flow at the end of this phase.
 - ► Since each iteration increases the flow by $\geq \Gamma/2$, if the current Δ -scaling phase continues for more than 2m iterations, then $\nu(f) \geq \nu(f') + 2m\Gamma/2 \geq \nu(\bar{f})$.

• Claim: the running time of the scaling max-flow algorithm is $O(m^2 \log C)$.

Other Maximum Flow Algorithms

- Running time of the Ford-Fulkerson algorithm is O(mC), which is *pseudo-polynomial*: polynomial in the magnitudes of the numbers in the input.
- Scaling algorithm runs in time polynomial in the size of the input (the graph and the number of bits needed to represent the capacities).

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- Desire a *strongly polynomial* algorithm: running time is depends only on the *size* of the graph and is *independent* of the numerical values of the capacities (as long as numerical operations take O(1) time).
- Edmonds-Karp, Dinitz: choose augmenting path to be the shortest path in G_f (use breadth-first search). Algorithm runs in O(mn) iterations.
- Improved algorithms take time $O(mn \log n)$, $O(n^3)$, etc.
- Chapter 7.4: Preflow-push max-flow algorithm that is not based on augmenting paths. Runs in $O(n^2m)$ or $O(n^3)$ time.